

# STA 141A – Fundamentals of Statistical Data Science

Department of Statistics; University of California, Davis

**Instructor:** Dr. Akira Horiguchi (ahoriguchi@ucdavis.edu)

**Ao1 TA:** Zhentao Li (ztlli@ucdavis.edu)

**Ao2 TA:** Zijie Tian (zjztian@ucdavis.edu)

**Ao3 TA:** Lingyou Pang (lyopang@ucdavis.edu)

## **Section 4: Basics in probability theory**

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## **SECTION 4: BASICS IN PROBABILITY THEORY**

- 1 Section 4: Basics in probability theory
  - Section 4.1: Probability measure and random variables
  - Section 4.2: PMF/PDF and CDF
  - Section 4.3: Some distributions
  - Section 4.4: Expected value
  - Section 4.5: Variance and covariance
  - Section 4.6: Conditional probability and independence

The prereq for this class is either STA 108 (regression) or STA 106 (ANOVA), so I expect you have already learned everything in this slide deck.

- If you need a refresher on probability, you can refer to this free textbook:  
<https://www.probabilitycourse.com/>

## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.1: PROBABILITY MEASURE AND RANDOM VARIABLES**

## Section 4.1 – Probability measure - Motivation

Probability is a way to quantify randomness and/or uncertainty.

- e.g., coin flips, dice rolls, stocks, weather.
- Rules of probability should be intuitive and self-consistent.
- Self-consistent: the rules shouldn't lead to contradictions.
- Thus these rules must be constructed in a certain way.
- Suppose we want to assign a probability to each event in a set of possible events.
- We would like, at the very least:
  - 1. each probability to be a value between 0 and 1 (inclusive)
  - 2. the probability assigned to the full set of events to be 1
  - 3. the probability assigned to the empty set to be 0
- We need more restrictions to ensure self-consistency.

The following definition will lead to intuitive and self-consistent rules of probability.

## Section 4.1 – Probability measure - Definition

### Definition 1: Probability measure $P(\cdot)$

For a nonempty set  $\Omega$ , the set function  $P: \Omega \rightarrow [0, 1]$  is a *probability measure*, if

- $P(\Omega) = 1$ , "Omega"
- for any pairwise disjoint sets  $A_1, A_2, \dots \subseteq \Omega$  (i.e.  $A_i \cap A_j = \emptyset$  for all  $i, j$  with  $i \neq j$ ), holds:

$$P\left(\bigcup_{i \in \mathbb{N}} A_i\right) = \sum_{i \in \mathbb{N}} P(A_i). \quad (1)$$

*Handwritten notes:* "union" with a downward arrow pointing to the union symbol; "A<sub>i</sub> & A<sub>j</sub> do not overlap" with a bracket over the condition; "empty set" with a line under the empty set symbol.

This definition fulfills the three properties from the previous slide:

- $P(\Omega) = 1$ : the probability of the biggest possible set is equal to 1.
- Property (1) allows us to add probabilities of disjoint sets.
  - ▶ Disjoint means having no shared elements.
  - ▶ (Property (1) is called the *countable additivity* property.)

## Section 4.1 – Probability measure - Properties

Definition 1 implies the following additional properties:

### Properties of $P(\cdot)$

With  $\emptyset$  being the empty set, with some sets  $A, B \subset \Omega$ , and with  $A^c = \Omega \setminus A$  denoting the complement of  $A$ , holds,

- i)  $P(\emptyset) = 0$ ;
- ii)  $P(A \cup B) = P(A) + P(B)$  if  $A \cap B = \emptyset$ ;
- iii)  $P(A^c) = 1 - P(A)$ ;
- iv)  $P(B \setminus A) = P(B) - P(A)$  if  $A \subseteq B$ ;
- v)  $P(A) \leq P(B)$  if  $A \subseteq B$ .

$\uparrow$   
"A complement"

(Pictures)



Probability measures allow us to characterize the "randomness" of events.

- But we are often interested in more than just probabilities. For example:
  - ▶ the number of heads from three (independent) flips of some coin
  - ▶ the sum of the faces after throwing two dice
  - ▶ the lifetime of a battery
- We call each of these a *random variable* because they take on different values based on random events.
- The probability that a random variable is a certain value will depend on the probabilities of individual events.



## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.2: PMF/PDF AND CDF**

When doing probability calculations, rather than use probability measures (which are functions of sets), it is often easier to describe a probability distribution using functions of single variables

1. PMF/PDF
2. CDF

The idea behind a PMF/PDF is to assign probabilities to the possible values of a random variable.

- The concept is different for discrete and continuous random variables.

## Section 4.2 – PMF/PDF - discrete and continuous case

A random variable  $X$  is *discrete* if its range is finite or countably infinite.

■ Examples:

1. number of heads after two coin flips,
2. number of coin flips needed before a heads turns up.

■ Here probabilities can be assigned to each realizable value. Examples:

1. For  $\{0, 1, 2\}$  (finite), we can assign probabilities  $1/4$ ,  $1/2$ , and  $1/4$ .
2. For  $\mathbb{N}$  (countably infinite), we can assign probabilities  $(1/2)^k$  to each  $k \in \mathbb{N}$ .

■ The *probability mass function* (PMF)  $f_X$  of a discrete random variable  $X$  assigns probabilities to each realizable value of  $X$ . Examples:

1.  $f_X(0) = 1/4$ ,  $f_X(1) = 1/2$ , and  $f_X(2) = 1/4$ .
2.  $f_X(k) = (1/2)^k$  for each  $k \in \mathbb{N}$ .

Here  $f_X(a)$  is “the probability that  $X$  equals  $a$ .”

■ The probability  $P(X \in A)$  that  $X$  lies in a set  $A$  can be calculated by

$$P(X \in A) = \sum_{a \in A} f_X(a), \quad \text{with} \quad f_X(a) := P(X = a). \quad (2)$$

■ It is common to plot the PMF.

## Section 4.2 – PMF/PDF - discrete and continuous case

A random variable  $X$  is *continuous* if its range is uncountably infinite.

- Examples: the lifetime of a battery, the lifetime of a person, the time it takes you to finish the first midterm exam
- For any value in the range of a continuous random variable  $X$ , the probability that  $X$  is that value must be zero. Why?
  - ▶ If uncountably many values are assigned positive probability, the sum of those values would then be infinity!

➔ ■ For a continuous random variable  $X$ , at any value  $a$  we have  $P(X = a) = 0$ .

- The *probability density function* (PDF)  $f_X$  of a continuous random variable  $X$  describes how likely it is for  $X$  to lie in a set  $A$  of values:

$$\underbrace{P(X \in A)} = \underbrace{\int_A \overbrace{f_X(s)}^{\text{PDF}} ds}_{\text{in } A} \quad (3)$$

- It is common to plot the PDF.

## Section 4.2 – PMF/PDF - discrete and continuous case

From the properties of probability measures, it follows that any PMF  $f_X$  of a discrete random variable  $X$  must satisfy both

1.  $f_X(x) \geq 0$  for all  $x$ , and
- 2.  $\sum_{\text{all } x} f_X(x) = 1$ .

Similarly, it follows that any PDF  $f_X$  of a continuous random variable  $X$  must satisfy both

1.  $f_X(x) \geq 0$  for all  $x$ , and
- 2.  $\int_{\text{all } x} f_X(x) dx = 1$ .

## Section 4.2 – CDF

The *cumulative distribution function* (CDF) of a random variable  $X$  is the function  $F_X: \mathbb{R} \rightarrow [0, 1]$  defined by

$$F_X(a) := P(X \leq a), \quad a \in \mathbb{R}. \quad (4)$$

This is “the probability that  $X$  is less than or equal to  $a$ .”

- Definition holds regardless of whether  $X$  is continuous or discrete.
- In the discrete case – recall Eq. (2) – holds for any  $a \in \mathbb{R}$ ,

$$F_X(a) = \sum_{s \leq a} f_X(s).$$

- In the continuous case – recall Eq. (3) – holds for any  $a \in \mathbb{R}$ ,

$$F_X(a) = \int_{-\infty}^a f_X(s) \, ds.$$

- From the definition in Eq. (4) come the following properties:
  1. The function  $F_X$  is (right-continuous) and monotonically increasing,
  2.  $\lim_{a \rightarrow -\infty} F_X(a) = 0$ ,
  3.  $\lim_{a \rightarrow \infty} F_X(a) = 1$ .

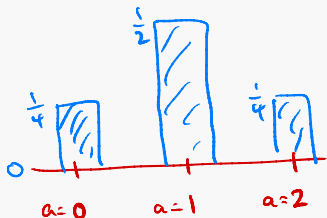
- For any  $a, b \in \mathbb{R}$  with  $b > a$  holds,

$$P(a < X \leq b) = \overbrace{F_X(b)}^{\text{CDF at } b} - \overbrace{F_X(a)}^{\text{CDF at } a}.$$

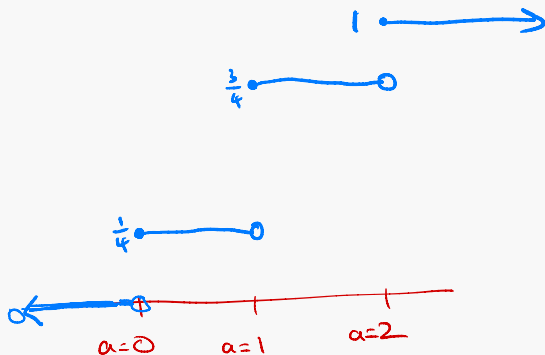
## Section 4.2 – CDF - relationship to PMFs

### Discrete random variables

PMF  $P(X=a)$



CDF  $P(X \leq a)$

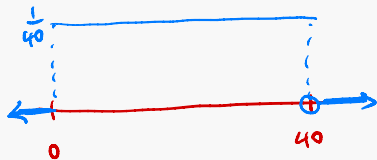




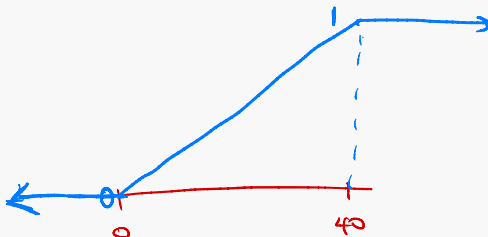
## Section 4.2 – CDF - relationship to PDFs

Continuous random variables

PDF  $f_x(a)$



CDF  $P(X \leq a) = \int_{-\infty}^a f_x(s) ds$



## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.3: SOME DISTRIBUTIONS**

## Section 4.3 – Discrete case - Uniform distr.

A random variable  $X$  with values in a finite set  $M$  is *uniformly* distributed if each element in  $M$  has the same probability:

$$P(X = k) = \frac{1}{\#M} \quad \text{for all } k \in M$$

- Such distributions occur when all possible outcomes are equally likely.
- We write  $X \sim U(M)$  or  $X \sim Unif(M)$ .
- Nine random draws in R:

```
sample(c(1,2,3,4,5,6), size=9, replace=TRUE)
```

## Section 4.3 – Discrete case - Bernoulli distr.

A random variable  $X$  is *Bernoulli* distributed with parameter  $p \in (0, 1)$ , if  $P(X = 1) = p$  and  $P(X = 0) = 1 - p$ .

- For when our random experiment has only two possible outcomes ("success" and "failure").
- Example: flip a coin with probability  $p$  of heads ("success"). Is it heads?
- We write  $X \sim \text{Ber}_p$  or  $X \sim \text{Bern}(p)$ .
- Nine random draws in R: `rbinom(n=9, size=1, prob=1/3)`

## Section 4.3 – Discrete case - Binomial distr.

A random variable  $X$  is *Binomial* distributed with parameters  $n \in \mathbb{N}$  and  $p \in (0, 1)$  if

$$P(X = k) = \binom{n}{k} p^k (1-p)^{n-k} \quad \text{for all } k = 0, \dots, n.$$

Handwritten notes and diagrams:  
- A blue arrow points from  $n!$  to  $k!(n-k)!$  in the binomial coefficient formula.  
- A red arrow points from the binomial coefficient to a list of outcomes: HTT, THT, TTH.  
- A red calculation shows  $\binom{3}{1} = \frac{3!}{1!2!} = 3$  outcomes with 1 success.  
- A red note says  $2^3$  total outcomes.  
- A blue arrow points to the  $k$  in the binomial coefficient.

- We think of  $n$  as the number of experiments and  $p$  the success probability. In the above equation,  $k$  is the number of successes.
- For measuring the probability of the number of successes of  $n$  independent Bernoulli experiments with parameter  $p$ .
- Example: flip a coin  $n$  times, each flip with probability  $p$  of heads ("success"). How many heads?
- We write  $X \sim \text{Bin}_{n,p}$  or  $X \sim \text{Bin}(n, p)$ .
- A random draw in R: `rbinom(n=3, size=1, prob=0.25) |> sum()`

## Section 4.3 – Continuous case - Uniform distr.

A random variable  $X$  is *uniformly* distributed on an interval  $M = (a, b)$ , with  $b > a$ , if the PDF has the form

$$f_X(x) = \begin{cases} \frac{1}{b-a} & \text{for all } x \in (a, b), \\ 0 & , \text{ otherwise} \end{cases} \quad \int_a^b \frac{1}{b-a} dx = 1$$

- Such distributions occur when all (uncountably many) possible outcomes are equally likely.
- The interval  $M$  can also instead be  $[a, b)$ , or  $(a, b]$ , or  $[a, b]$ .
- Here we also write  $X \sim U(M)$  or  $X \sim \text{Unif}(M)$ .
- Nine random draws in (3, 5) in R: `runif(n=9, min=3, max=5)`

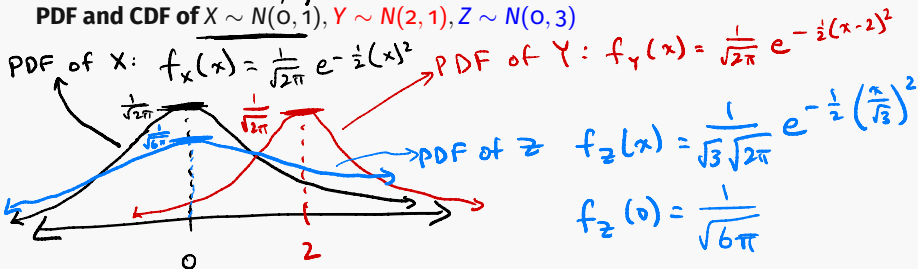
## Section 4.3 – Continuous case - Normal distr.

A random variable  $X$  is *normally* distributed with parameters  $\mu \in \mathbb{R}$  and  $\sigma^2 > 0$ , if the PDF has the form

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2} \quad \text{for all } x \in \mathbb{R}. \quad \begin{matrix} \uparrow & \uparrow \\ \text{"mu"} & \text{"sigma squared"} \end{matrix}$$

- This distribution appears often in this class, in future classes, and in life!
- We write  $X \sim N(\mu, \sigma^2)$ . We also call it *Gaussian* distributed.
- Thereby,  $E(X) = \mu$  (location parameter), and  $\text{Var}(X) = \sigma^2$  (squared scale).
- If  $X \sim N(0, 1)$ , the distribution of  $X$  is said to be *standard normal*.
- Nine random draws in R: `rnorm(n=9, mean=2, sd=1)`  $N(2, 1^2)$

PDF and CDF of  $X \sim N(0, 1)$ ,  $Y \sim N(2, 1)$ ,  $Z \sim N(0, 3)$



## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.4: EXPECTED VALUE**



## Section 4.4 – Expected value - Introduction

The expected value of a random variable is the weighted average of all of its **values**, where the **weights** are the probabilities that these values occur.

### Definition 2: Expected value $E(\cdot)$

Let  $X$  be a random variable. Then, the *expected value* of  $X$  is in the discrete case and in the continuous case (given the PDF  $f_X$ ) is defined as

$$E(X) = \sum_{\text{all } k} \overbrace{P(X=k)}^{\text{weight}} \cdot \overbrace{k}^{\text{value}} \quad \text{resp.} \quad E(X) = \int_{\text{all } s} \overbrace{f_X(s)}^{\text{weight}} \cdot \overbrace{s}^{\text{value}} ds. \quad (5)$$

*discrete* *continuous*

- The expected value of a random variable sometimes does not exist if, for example, the random variable is continuous and the weights are "large" for large values of the random variable (e.g.  $E(X) = \int_1^\infty \frac{1}{s^2} \cdot s ds = \infty$ ).

## Section 4.4 – Expected value - Calculating expected value by hand

Calculate  $E(X)$  with PDF  $f_X(a) = \frac{3}{7}a^2$  where  $a \in [1, 2]$

$$E(X) = \int_1^2 f_X(a) a \, da$$

$$= \int_1^2 \frac{3}{7} a^2 a \, da$$

$$= \frac{3}{7} \int_1^2 a^3 \, da$$

$$= \frac{3}{7} \left. \frac{a^4}{4} \right|_{a=1}^{a=2}$$

$$= \frac{3}{7} \left[ \frac{2^4}{4} - \frac{1^4}{4} \right]$$

$$= \frac{3}{7} \cdot \frac{15}{4} = \boxed{\frac{45}{28}}$$

## Section 4.4 – Expected value - Calculation tools

### Properties of $E(\cdot)$

Let  $c \in \mathbb{R}$  be a constant, and let  $X, Y$  be random variables for which their expected values  $E(X)$  and  $E(Y)$  exists. Then, the following rules hold.

- i)  $E(c) = c$ ;
- ii)  $E(cX) = cE(X)$ ;
- iii)  $E(X + Y) = E(X) + E(Y)$ .

**Example with**  $c = 2$ ,  $E(X) = 1$ ,  $E(Y) = 5$

i)  $E(2) = 2$

ii)  $E(2X) = 2E(X) = 2$

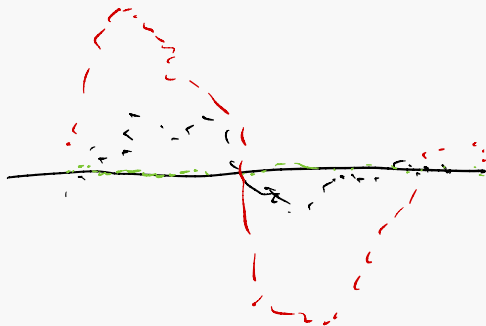
iii)  $E(X + Y) = E(X) + E(Y) = 1 + 5 = 6$   
 $E_X + E_Y$

## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.5: VARIANCE AND COVARIANCE**

## Section 4.5 – Variance - Introduction

**Heuristics** "How much values vary about their mean"



## Section 4.5 – Variance - Definition and properties

The variance of a random variable is the expected squared deviation of its values to its expected value.

### Definition 3: Variance $\text{Var}(\cdot)$

Let  $X$  be a random variable with  $E(X^2) < \infty$ . Then the *variance* of  $X$  is defined as

$$\text{Var}(X) := E[\underbrace{\{X - E(X)\}^2}_{\xi X - EX}]. \quad (6)$$

Think of  $\text{Var}(X)$  as “how much  $X$  varies about its mean.” We can deduce:

- $\text{Var}(X) \geq 0$ .
- $\text{Var}(X) = 0 \Rightarrow X$  is constant.
- The variance of  $X$  can also be calculated as

$$\text{Var}(X) = E(X^2) - (E(X))^2. \quad (7)$$

## Section 4.5 – Variance - Calculation tools

### Properties of $\text{Var}(\cdot)$

Let  $c \in \mathbb{R}$  be a constant, and let  $X$  be a random variable with  $E(X^2) < \infty$ . Then

- i)  $\text{Var}(c) = 0$ ;
- ii)  $\text{Var}(X + c) = \text{Var}(X)$ ;
- iii)  $\text{Var}(cX) = c^2 \text{Var}(X)$ ;

Recall intuition:  $\text{Var}(X)$  is “how much  $X$  varies about its mean.”

**Example with**  $c = 5$ ,  $\text{Var}(X) = 1$ ,  $\text{Var}(Y) = 2$ .

- i)  $\text{Var}(5) = 0$
- ii)  $\text{Var}(X + 5) = \text{Var}(X) = 1$
- iii)  $\text{Var}(5X) = 25 \text{Var}(X) = 25$

## Section 4.5 – Covariance and correlation - Motivation

Expected value and variance help characterize the distribution of a single random variable  $X$ .

Now suppose we want to characterize the relationship between two random variables  $X$  and  $Y$ .

- A complete characterization requires assigning probabilities to every possible pair of values that  $(X, Y)$  could be.
- Simpler characterizations are the *covariance* and *correlation* of  $X$  and  $Y$ .



### Heuristics

## Section 4.5 – Covariance - Definition and properties

### Definition 4: Covariance $\text{Cov}(\cdot, \cdot)$

Let  $X, Y$  be random variables with  $E(X^2), E(Y^2) < \infty$ . Then the *covariance* between  $X$  and  $Y$  is defined as

$$\text{Cov}(X, Y) := E((X - E(X))(Y - E(Y))). \quad (8)$$

- The covariance between  $X$  and  $Y$  can also be calculated as

$$\text{Cov}(X, Y) = E(XY) - E(X)E(Y). \quad (9)$$

- We say  $X$  and  $Y$  are *uncorrelated* if  $\text{Cov}(X, Y) = 0$ . Then  $X$  and  $Y$  have no linear relationship, and  $E(XY) = E(X)E(Y)$ .
- $\text{Cov}(X, Y) > 0$  indicate a positive linear relationship between  $X$  and  $Y$ .
- $\text{Cov}(X, Y) < 0$  indicate a negative linear relationship between  $X$  and  $Y$ .
- Covariance is symmetric:  $\text{Cov}(X, Y) = \text{Cov}(Y, X)$ .

## Section 4.5 – Correlation coefficient

### Definition 5: Correlation coefficient $\rho(\cdot, \cdot)$

Let  $X, Y$  be random variables with  $E(X^2), E(Y^2) < \infty$ . Then, the *correlation coefficient* between  $X$  and  $Y$  is defined as, provided  $\text{Var}(X) > 0$  and  $\text{Var}(Y) > 0$ ,

$$\rho(X, Y) := \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X)}\sqrt{\text{Var}(Y)}} \in [-1, 1]. \quad (10)$$

- $\rho(X, Y) = 0 \Rightarrow$  between  $X$  and  $Y$  is no linear relationship.
- $\rho(X, Y) = -1$  ( $1$ )  $\Rightarrow$  all values of  $X$  and  $Y$  lie on a line with negative (positive) slope.
- If  $\rho(X, Y)$  is close to  $-1$  ( $1$ ), there is a strong negative (positive) linear relationship between  $X$  and  $Y$ .

## Section 4.5 – Variance and covariance - More calculation tools

### Properties of $\text{Var}(\cdot)$ and $\text{Cov}(\cdot, \cdot)$

Let  $c \in \mathbb{R}$  be a constant, and let  $X, Y, Z$  be random variables with  $E(X^2) < \infty$ ,  $E(Y^2) < \infty$ , and  $E(Z^2) < \infty$ . Then

- iv)  $\text{Var}(X) = \text{Cov}(X, X)$
- v)  $\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$
- vi)  $\text{Cov}(X, Y) = \text{Cov}(Y, X)$
- vii)  $\text{Cov}(X + Y, Z) = \text{Cov}(X, Z) + \text{Cov}(Y, Z)$  and  $\text{Cov}(cX, Z) = c\text{Cov}(X, Z)$

(Property vii says  $\text{Cov}(\cdot, \cdot)$  is linear in its first argument. Because  $\text{Cov}(\cdot, \cdot)$  is symmetric, it is also linear in its second argument. Thus we call it *bilinear*.)

**Example with**  $c = 5$ ,  $\text{Var}(X) = 1$ ,  $\text{Var}(Y) = 2$ ,  $\text{Cov}(X, Y) = 1/3$ .

## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.6: CONDITIONAL PROBABILITY AND INDEPENDENCE**

### Heuristics

## Section 4.6 – Definition and properties

An *event* is a subset of the sample space  $\Omega$ .

### Definition 6: Conditional probability

For events  $A, B \subseteq \Omega$ , the *conditional probability* of  $A$  given  $B$  is defined by

$$P(A|B) = \begin{cases} \frac{P(A \cap B)}{P(B)}, & \text{if } P(B) > 0, \\ 0, & \text{if } P(B) = 0. \end{cases} \quad (11)$$

- Events  $A$  and  $B$  are called *independent* if

$$P(A \cap B) = P(A)P(B). \quad (12)$$

Here knowing  $B$  provides no information about  $A$ , and vice versa.

- Equivalently, events  $A$  and  $B$  are independent if  $P(A|B) = P(A)$ .
- Random variables  $X$  and  $Y$  are called *independent* if for all sets  $A, B$  holds,

$$P(X \in A, Y \in B) = P(X \in A)P(Y \in B). \quad (13)$$

- Independent random variables are uncorrelated.
- But uncorrelated random variables are not necessarily independent!